



# Wet Gas Performance of Coriolis Meters: Continuation of Laboratory and Field Evaluation

David Morett  
James Deacy



# Content

Introduction

Brief Overview of Coriolis Technology

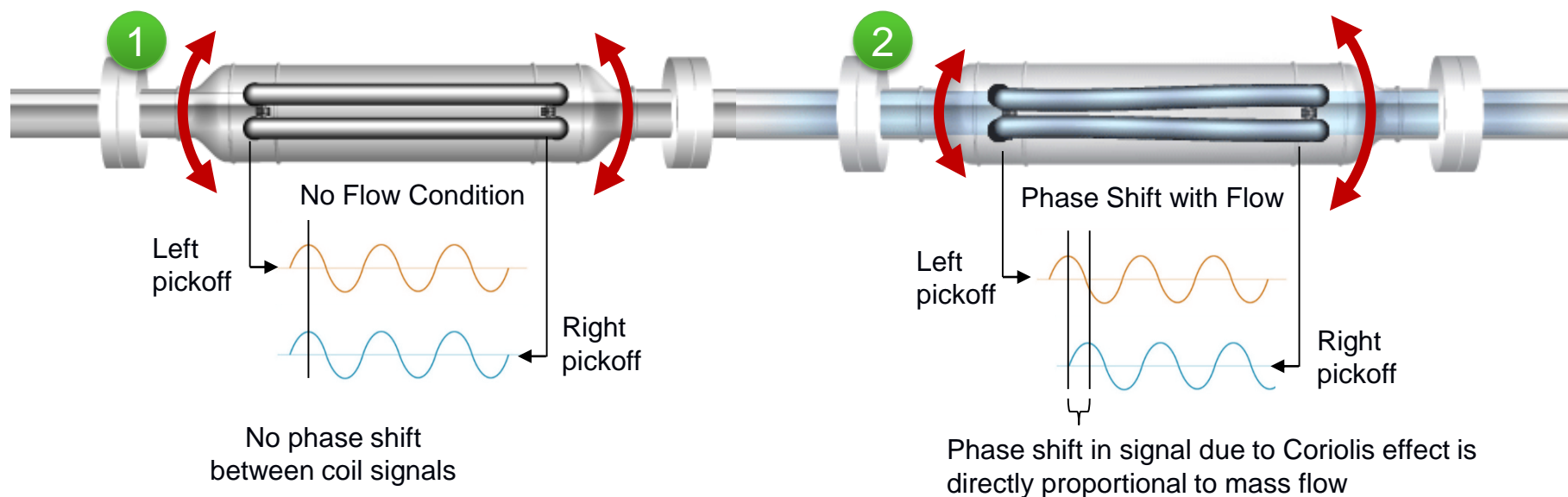
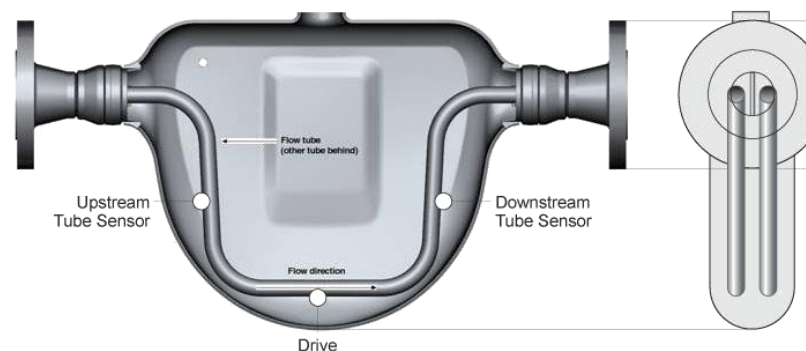
Critical Designs Elements for Wet Gas or Multiphase Use

Algorithm Options for Different Conditions

Latest Results from Testing

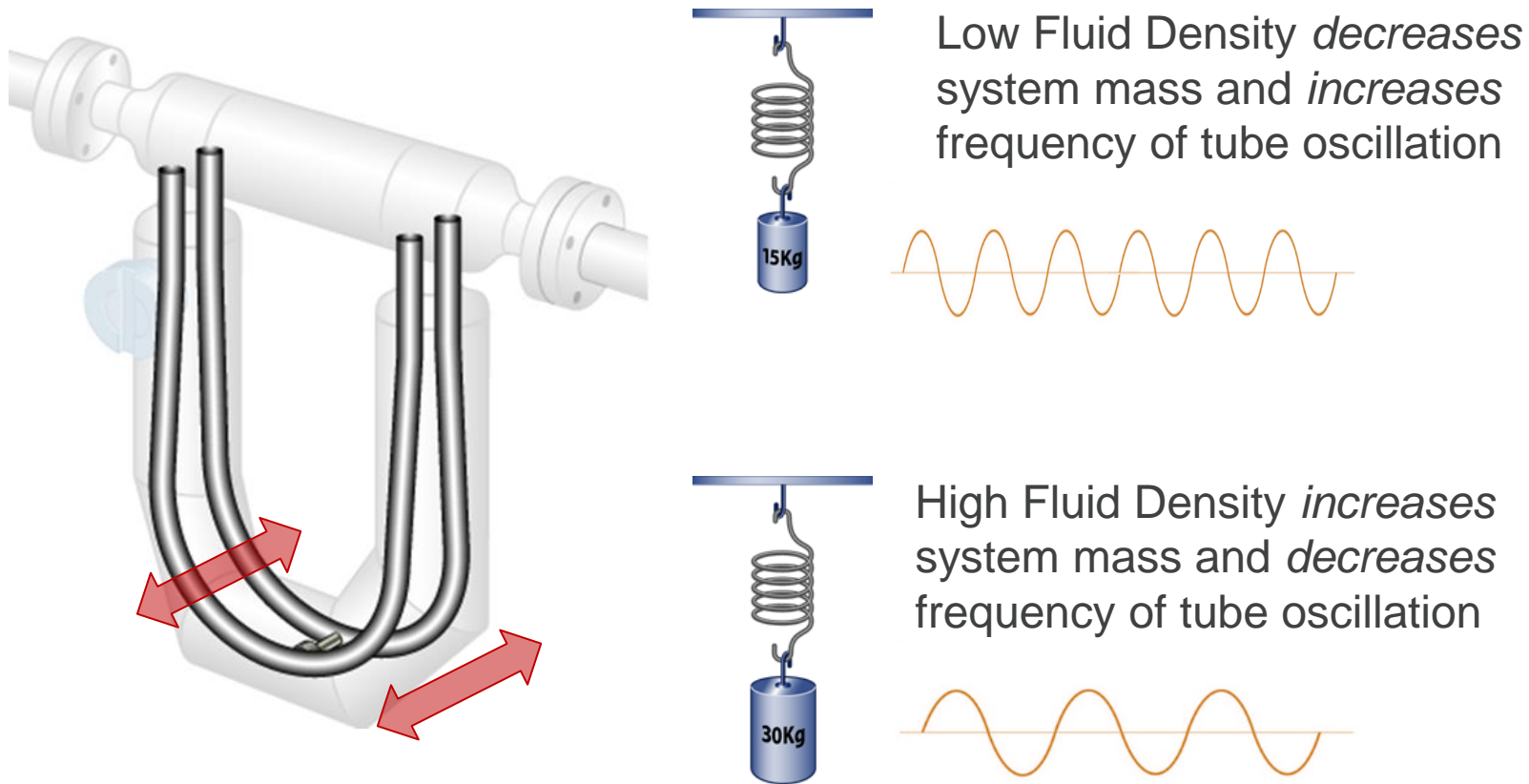
# Theory of Operation – The Coriolis Effect

- 1 During a no flow condition, flow tubes vibrate in phase with each other.
- 2 With flow, Coriolis forces are induced causing the flow tubes to twist in opposition to each other.



**Phase shift between pickoff coils is directly proportional to mass flow**

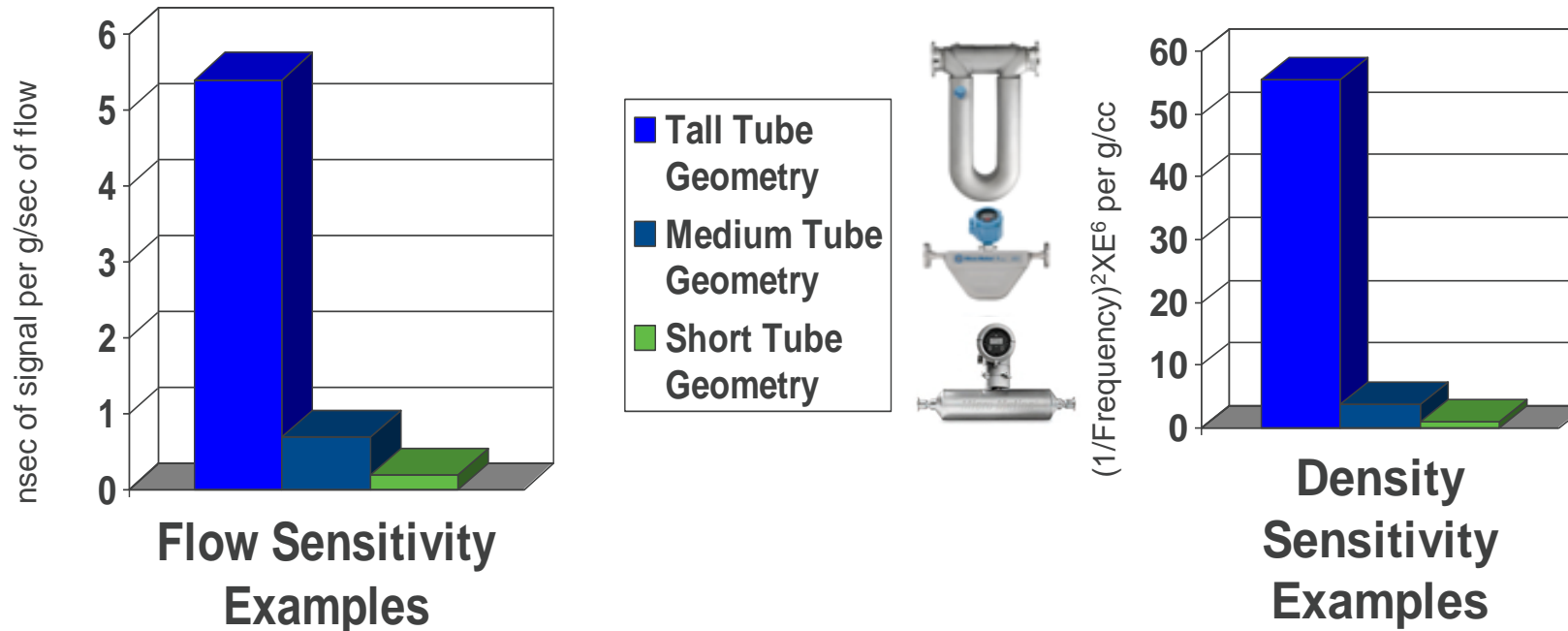
# Theory of Operation - Density



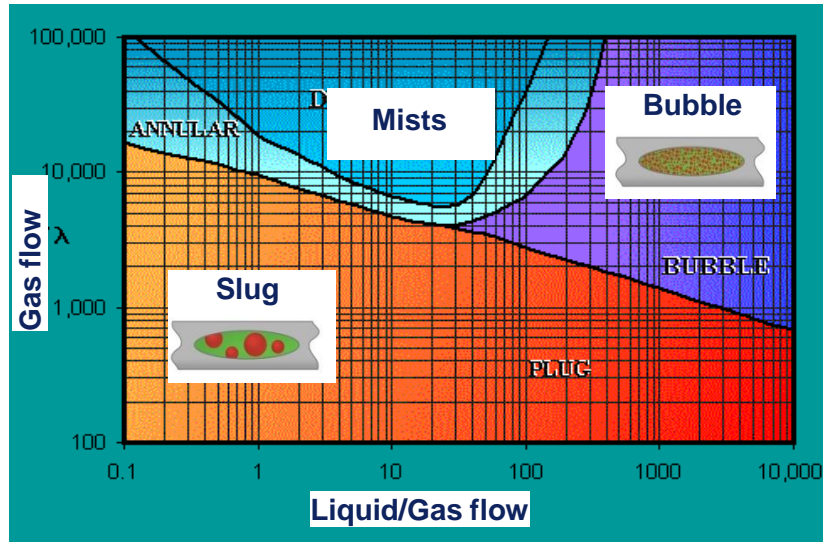
**Density measurement is based on the natural frequency of the system, including the flow tubes and the process fluid.**

# Coriolis Meter Raw Sensitivity Varies with Design

- **Raw Sensitivity Depends on Tube Geometry**
- **Signal to Noise Ratio Depends on Raw Sensitivity and Stability**
- **Accuracy, Stability, Calibration Flexibility, Immunity to Secondary Effects, and Diagnostic Capabilities Depend on Signal to Noise Ratio**



# Improvements to Handle Multiphase Regimes

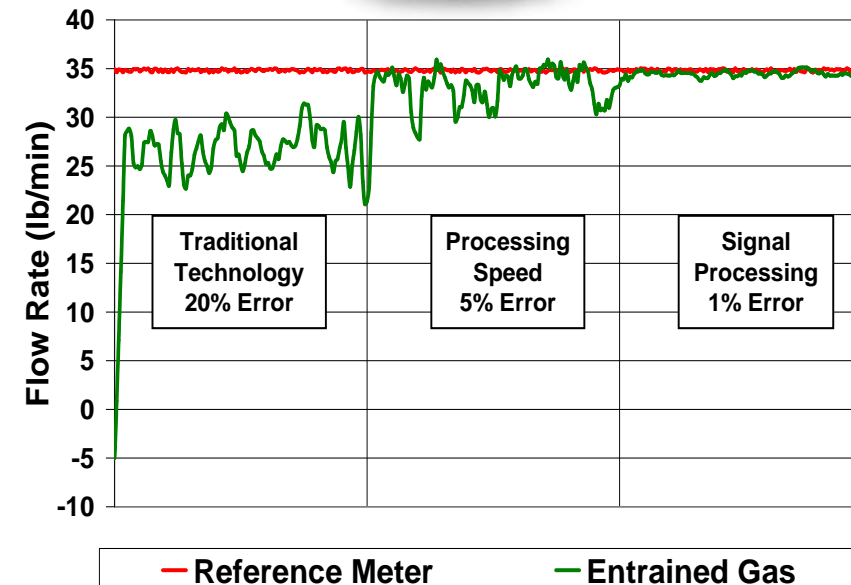


## Electronics Improvements

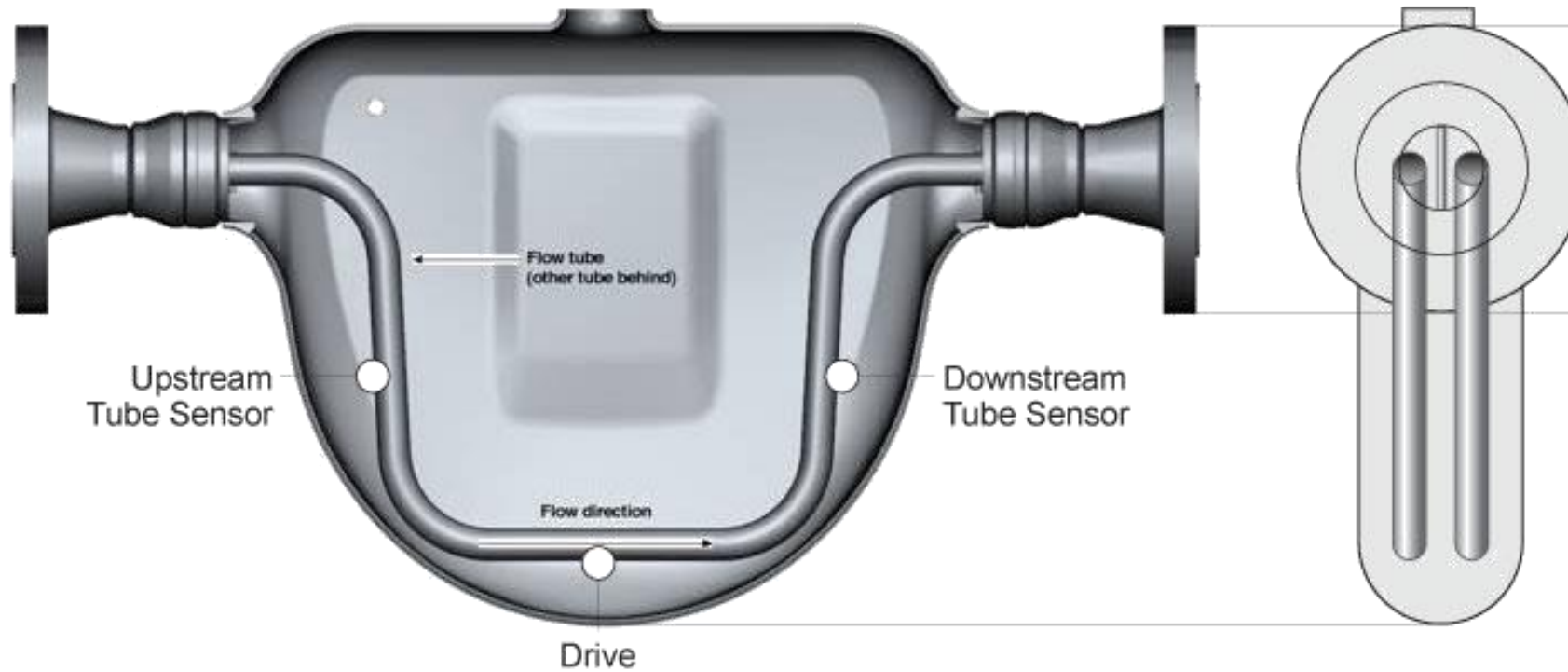
- Processing speed
- Signal processing algorithms
- Function with noisy signals

## Structural Improvements

- Better balance and vibration isolation
- Modal separation



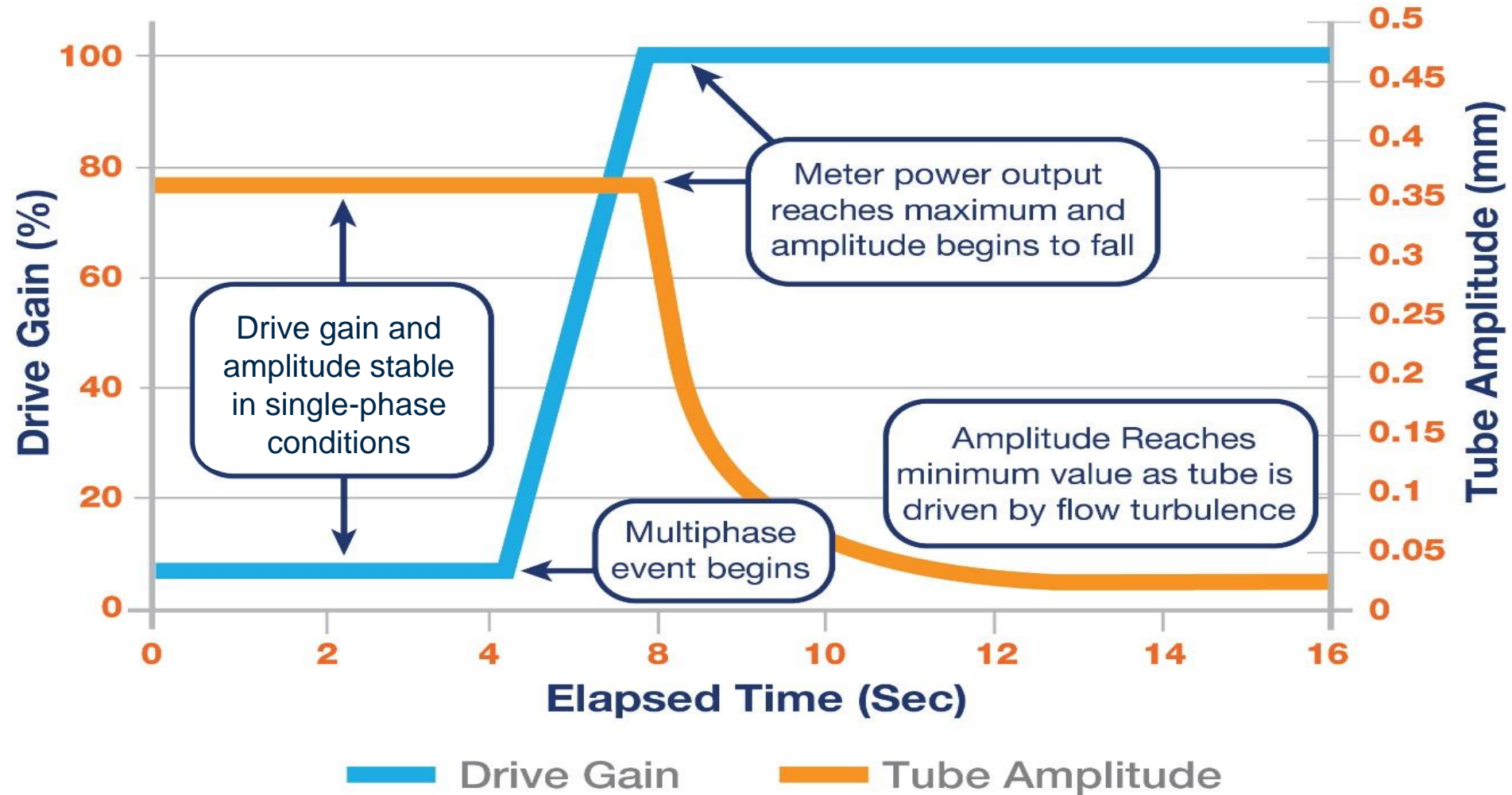
# Vibration Drive and Amplitude



**Drive and pickoff coils provide damping data**



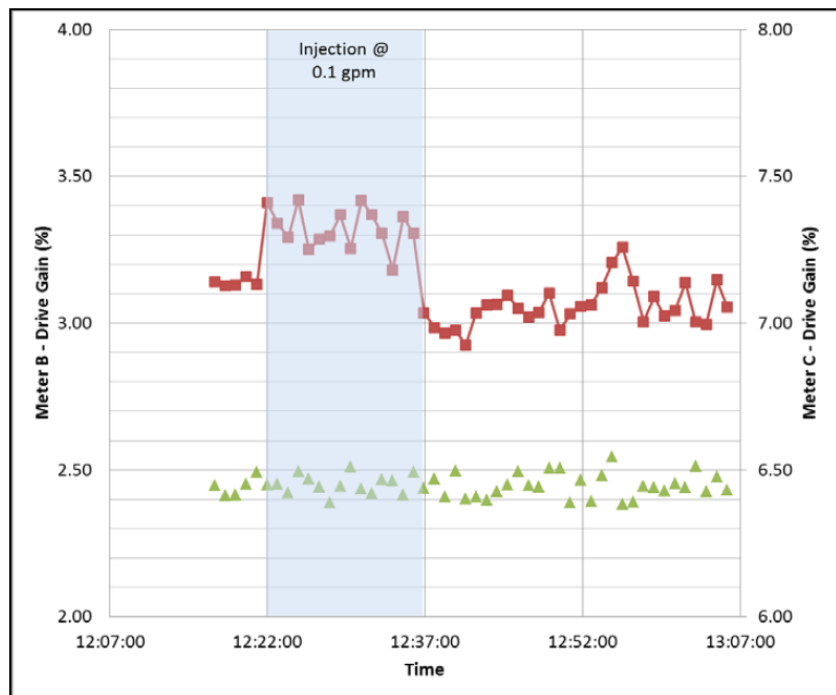
# Detection of Multiple Phases



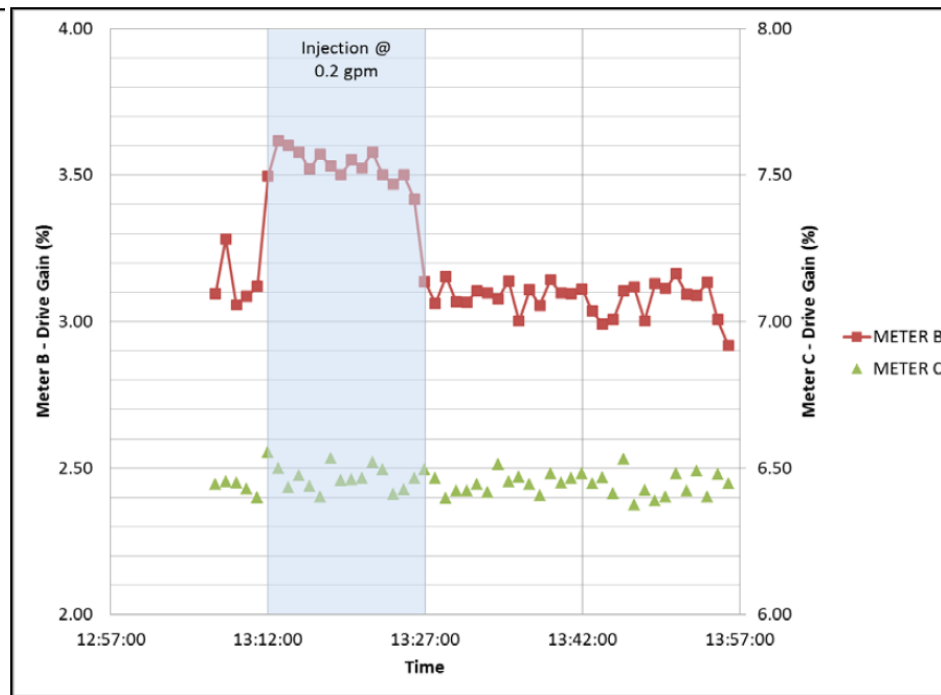
Damping of flow tubes indicates multiple phases



# Lab Testing: Sensitivity to Liquid Phase



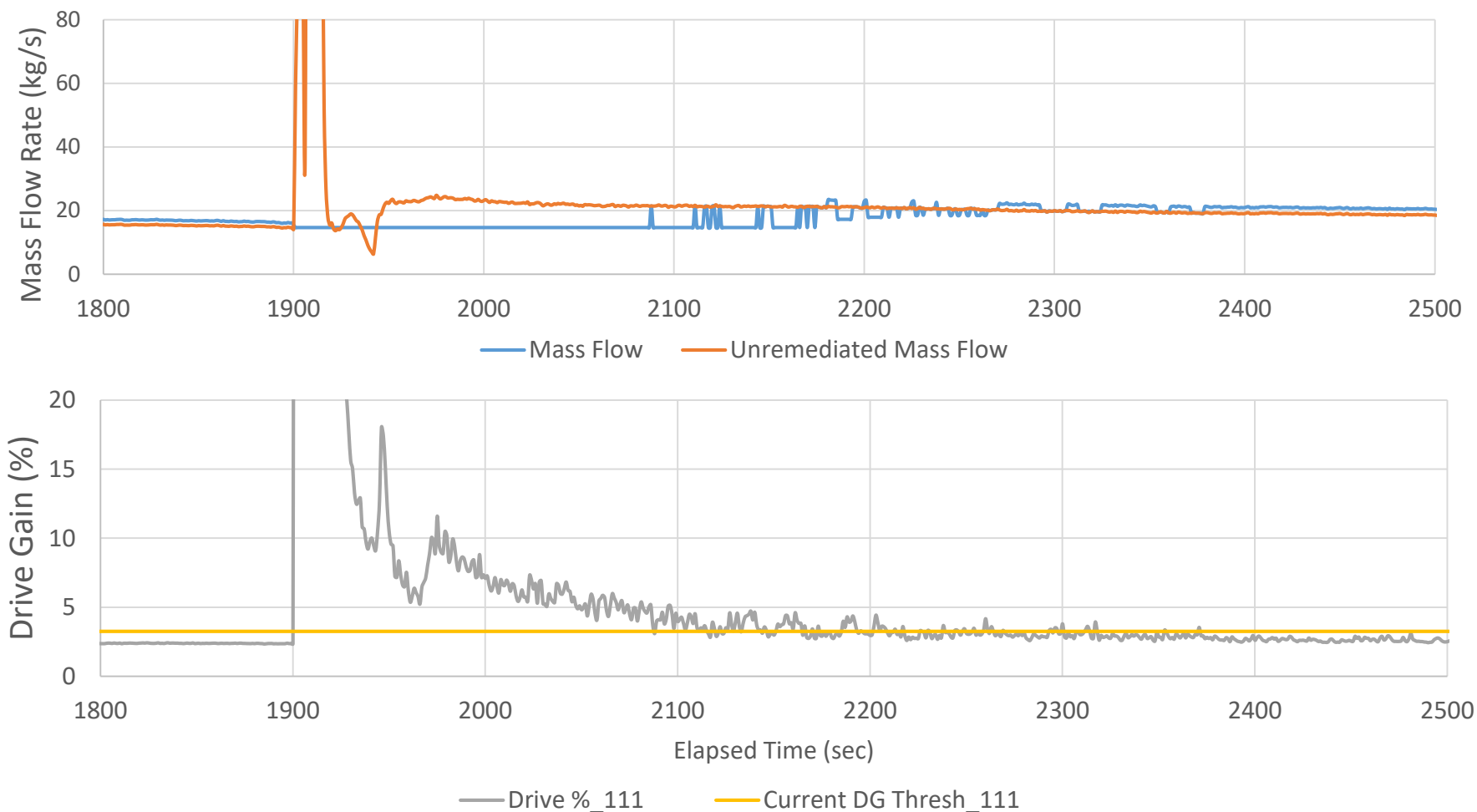
Drive Gain Results for Meter B at 100 acfm and 0.1 gpm



Drive Gain Results for Meter B at 100 acfm and 0.2 gpm

**Sensor element design, signal processing and control of vibration has effect on ability to detect phase contamination**

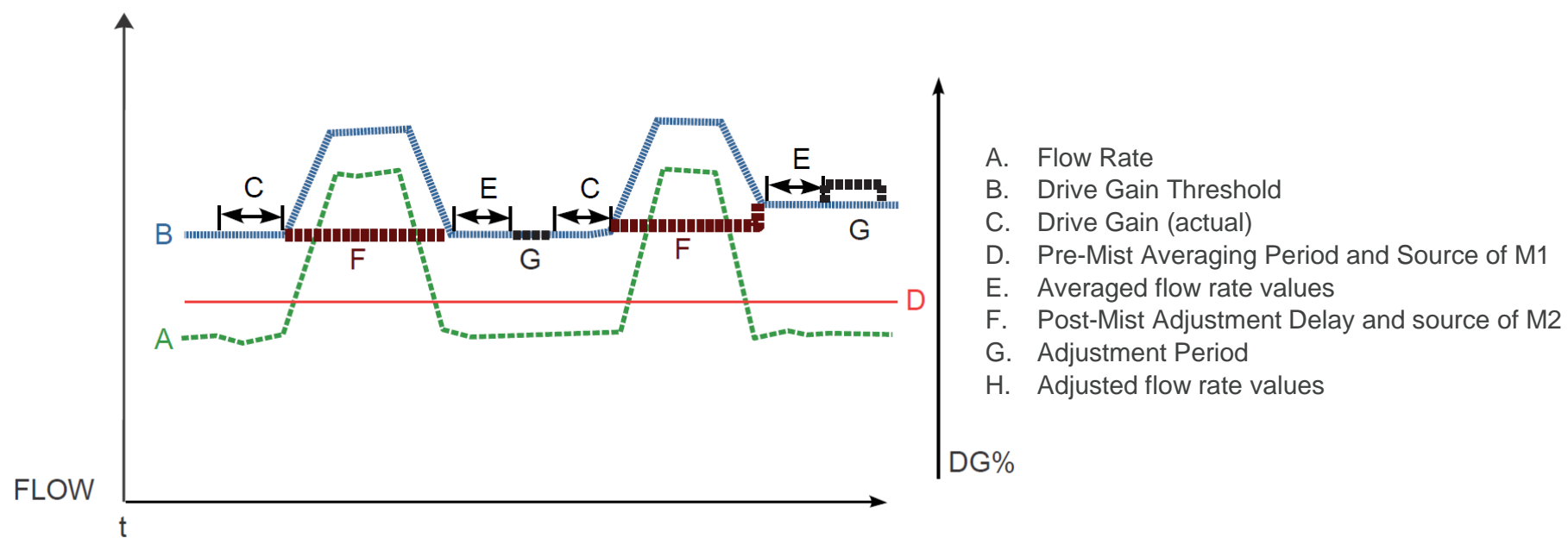
# Field Data: Liquid Slugs in Gas



**Immediate detection of liquid slugs allows them to be excluded from gas measurement**

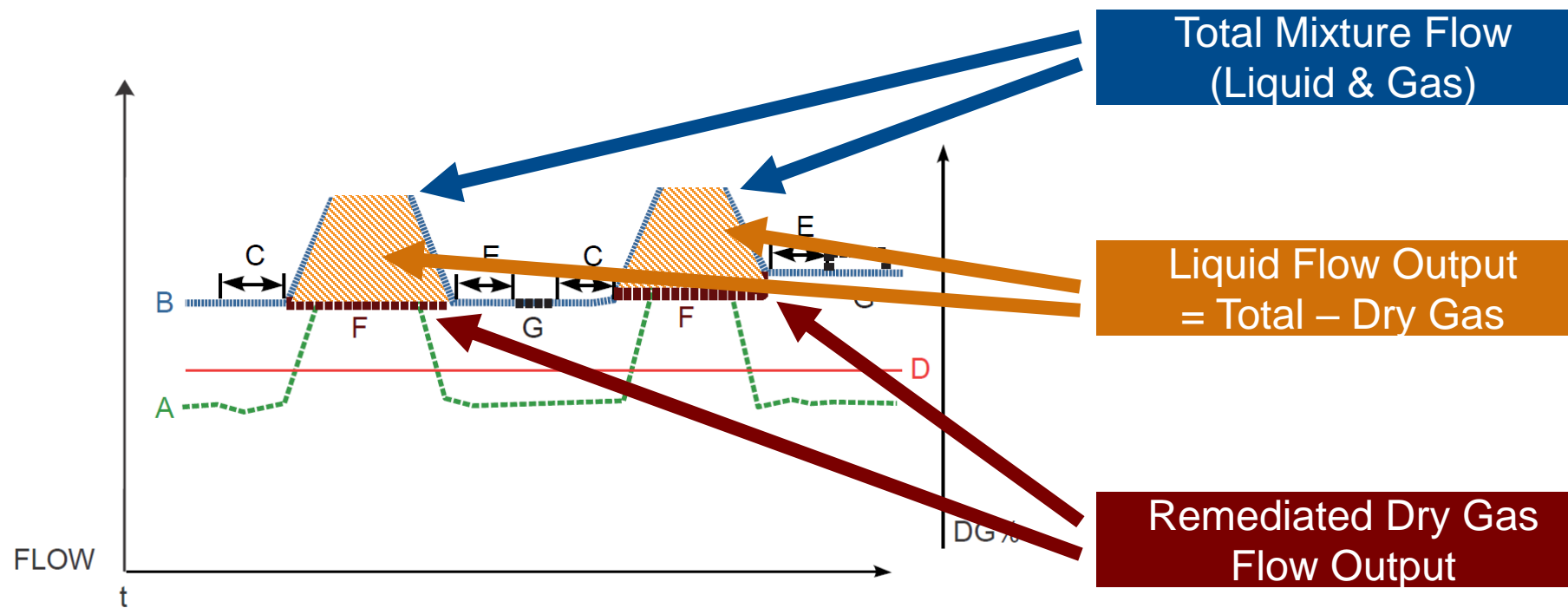


## Simple Wet Gas Algorithm

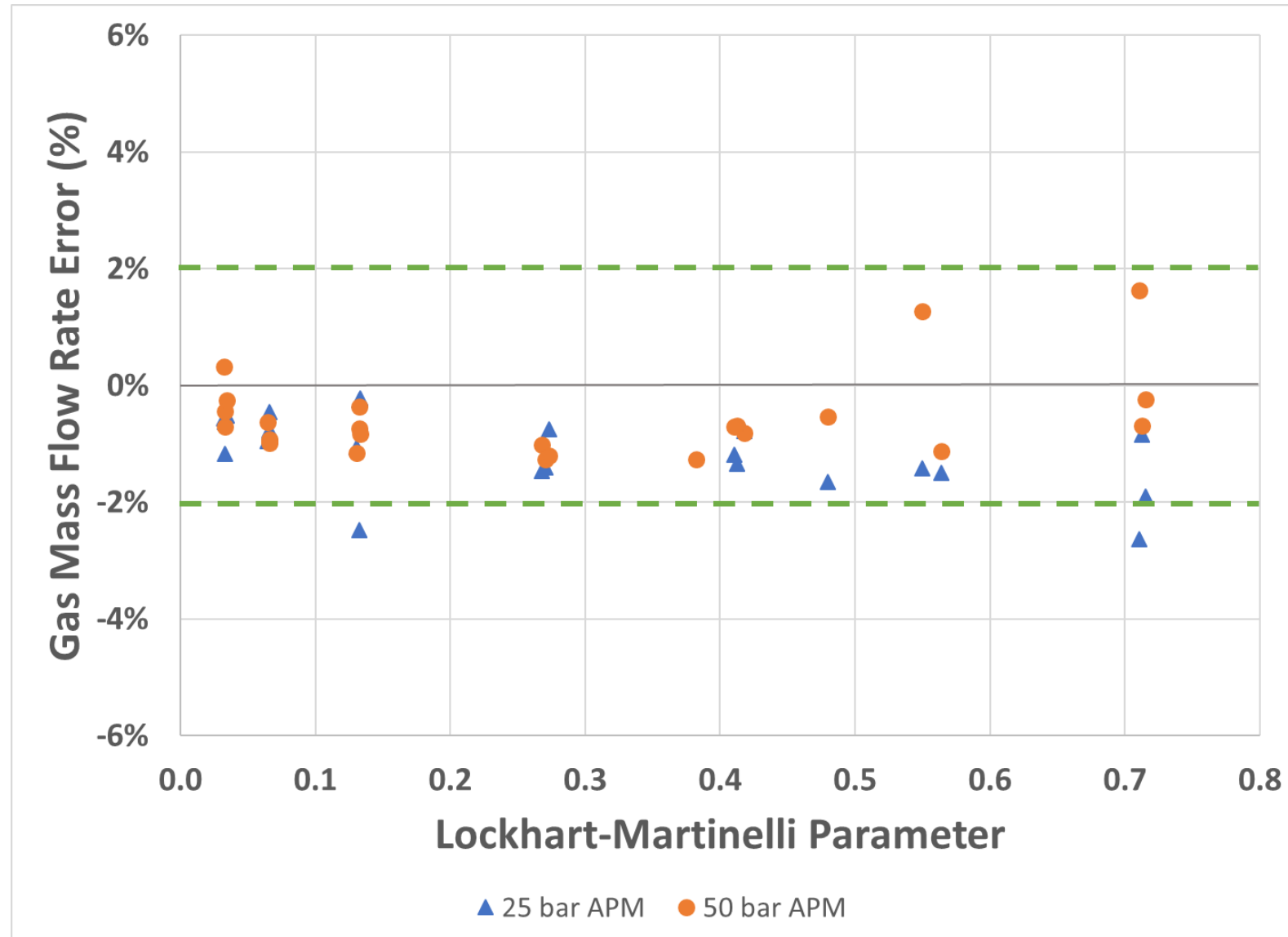




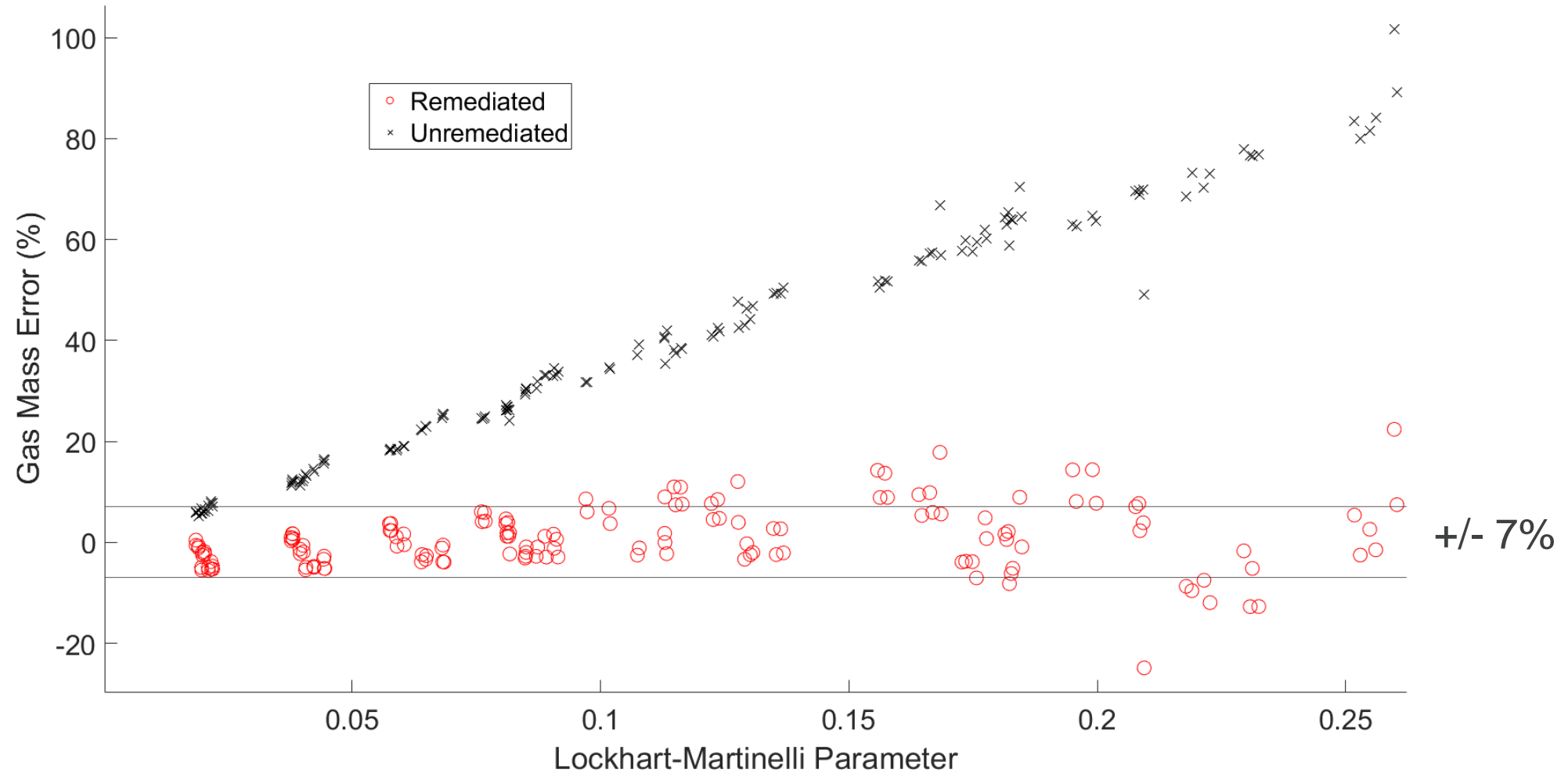
## Simple Wet Gas Algorithm



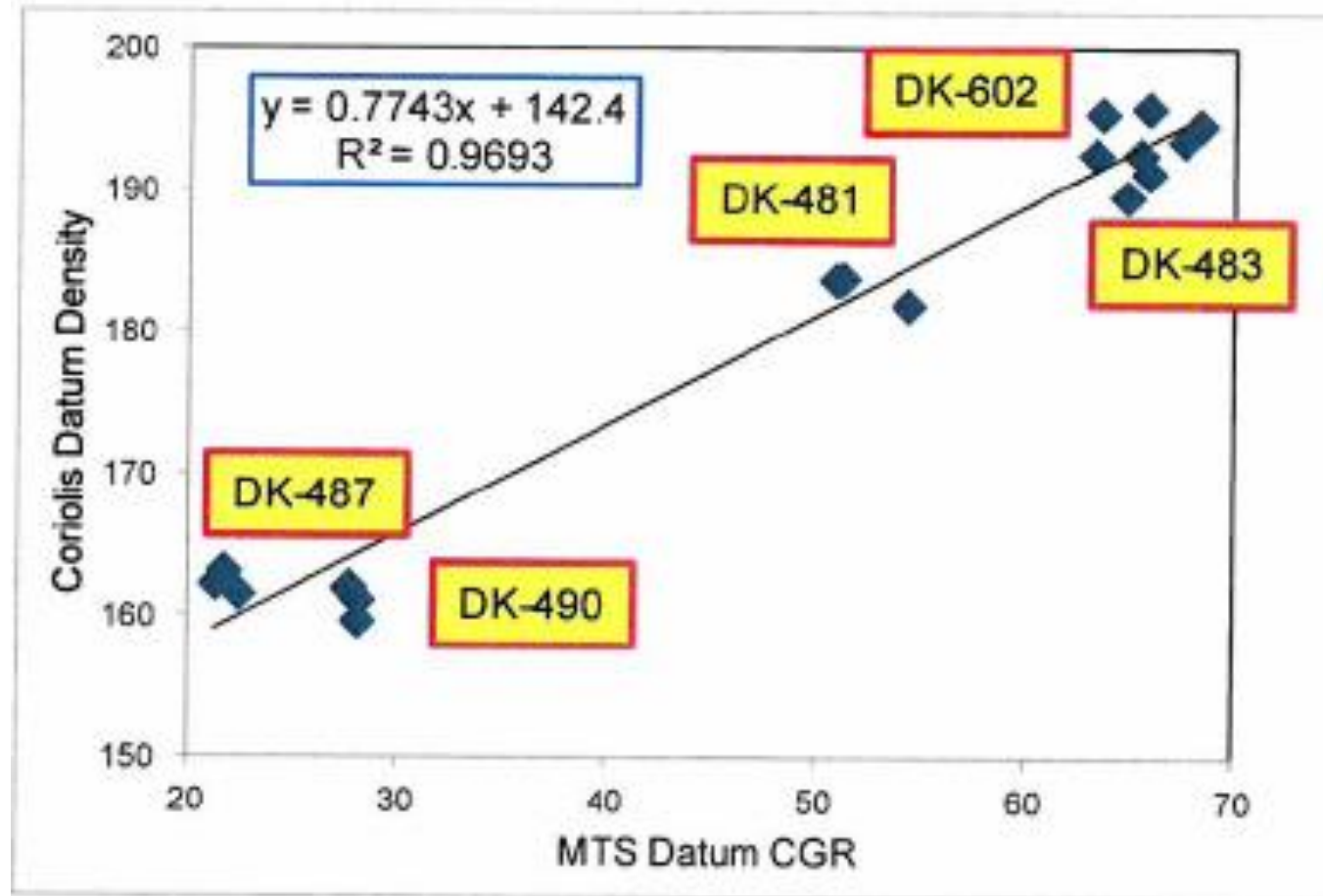
# CEESI Testing – Slugging Regime



# Lab Testing: Continuous Wet Gas



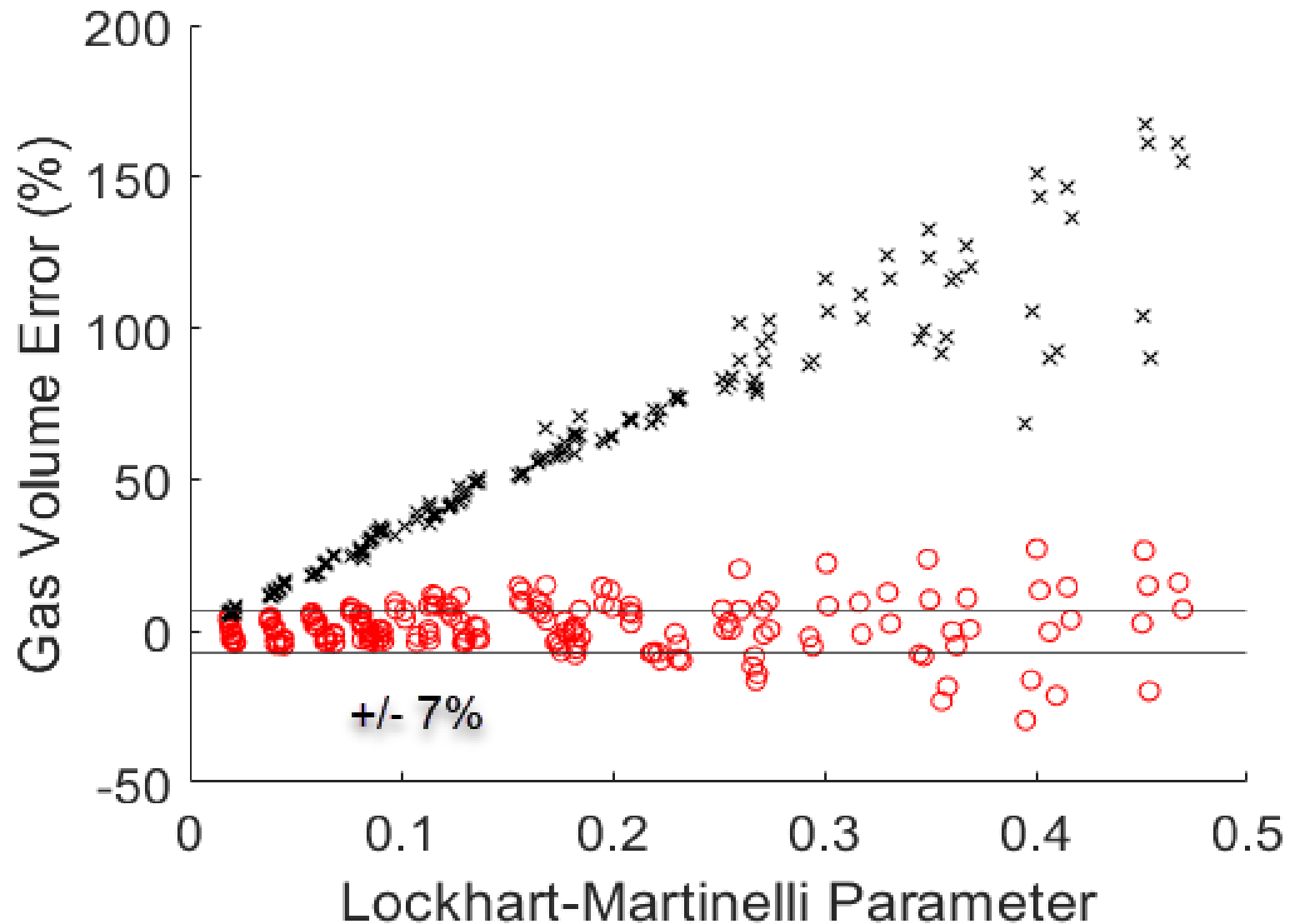
# Field Data: Determining Liquid Content



A useable approach in the field is to use well tests to reference measured density to phase fractions



## Extending Corrections for More Liquid



# Experience in the Field

---

- **Field conditions always more challenging than lab**
  - Different process conditions, fluid properties, hydrates, solids
  - Questionable references
- **Thousands of meters in the field using intermittent multiphase algorithm**
  - Separator outlets, plunger lift wells, naturally slugging regimes
  - Generally accepted to be within  $\pm 3\%$  GSV over broad range of pressure, temperature, flow rate and liquid loading conditions
- **Field trials underway on continuous / changing regime wet gas**
  - Initial results within uncertainty of field reference:  $\pm 7\%$  GSV
  - Primary challenge is hydrate formation
  - Tracking field operational changes that could affect trial also a challenge

# Summary

---

- Coriolis technology has improved in the past ~10 years
  - Time to revisit guidelines for wet gas use
- Not all Coriolis designs are expected to have the same behavior in multiphase or wet gas
- It appears that viable methods exist to correct flow outputs
  - Coriolis meters can provide regime data, depending on design
  - May be less reliant on external inputs than existing approaches
    - Meter can measure liquid content and detect hydrates
- Additional research needed, revisit guidance on coriolis suitability for wet gas applications
  - Need to address field implementation challenges



## Contact Us

David Morett

James Deacy

Emerson

7070 Winchester Cir, Boulder, CO  
USA

[www.emerson.com](http://www.emerson.com)

[david.morett@emerson.com](mailto:david.morett@emerson.com)

+1.303.516.8688

<http://www.emerson.com/en-us/automation/micro-motion>