Extended Abstract

Ultrasonic measurement of liquid carbon dioxide

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1 INTRODUCTION

In recent years, CCS (Carbon Capture and Storage) has gained attention as a possible means of meeting our global climate improvement goals. With CCS demonstration projects under development, there is a need to focus on the widespread deployment of CCS and the technologies needed to make it viable. Upscaling CCS demand reliable and accurate metering of CO₂ for fiscal, commercial, and regulatory purposes. Accurate measurement of CO₂ streams is crosscutting along the CCS value chain and is an enabler for CCS business. Dependable flow measurements are paramount to ensuring safe operation of CC₂ systems, complying with regulations, and enabling global fair trade of 5 Gt of CO₂ per year by 2050, ultimately warranting the CCS business model.

Several CCS projects are currently under development. The planning construction and of the infrastructure needed to transport CO₂ from industrial capture sites to the geological storage formations are well underway in various European locations. Throughout the CCS value chain, CO2 will be transported in multiple fluid states 1), i. e. , (i) as a (see Fig. pressurised liquid or dense phase in export or offshore pipelines, (ii) as a refrigerated liquid for longdistance bulk shipping transport, and (iii) as pressurised gas for short-distance transport onshore. The present work focuses on the former two transport methods (i. e. liquid only).



Fig. 1 – Operational conditions of CO₂ transport streams for CCS

Recent benchmarking studies agree that the CCS industry could benefit from the measurement capabilities developed and fostered in the oil and gas industry, where numerous metering techniques coexist [1, 2]. Ultrasonic flow measurement technology is promising for CCS, given the ability of such meters to handle large volumetric flow rates through large pipe sizes using a single metering unit. To date, verification tests of the ultrasonic technology for measuring liquid CO₂ have been limited to enhanced oil or gas recovery (EOR or EGR) operations or extraction of CO₂-rich natural gas. The potential use of ultrasonic meters for CCS has yet to be thoroughly tested and confirmed.

Extended Abstract

In this context, the present study highlights the capabilities and some areas of needed improvement to use such meters for liquid CO₂ service. This extended abstract derives from an experimental campaign undertaken by SINTEF Energy Research in collaboration with Panametrics, a Baker Hughes business. The work, available in [3], looked into the performance of a four-path ultrasonic flow meter during static liquid CO₂ testing. The observations discussed here and the challenges identified are a stepping stone towards understanding the implications of sound attenuation in CCS streams for ultrasonic meter technology.

2 Ultrasonic metering

Ultrasonic flow meters measure flow using the "time of flight" or transit-time

method for calculating flow velocity and, therefore, volumetric flow rate. Every pair of facing transducers alternately sends and receives ultrasonic sound pulses. In every cycle, the electrical signal is converted into ultrasonic pulses at the transmitting side and then converted back to electrical energy by the receiving transducer. The transit times between the signals in the upstream downstream directions and are recorded. When the transducers are placed at an angle against the flow direction (θ) , the signal sent in the downstream direction will have a shorter transit time than the signal



Fig. 3 – Tests points



Fig. 2 – Cutout of the ultrasonic flow meter.

sent in the upstream direction. Hence, the direct, linear relationship between the fluid velocity versus the recorded difference in transit times (also called "delta-t" or Δt). Multiple transducer pairs give increased confidence and accuracy in results. The ultrasonic meter used has four measurement paths arranged in chords across the meter body, as illustrated in Fig. 2.

Factors like fluid viscosity, temperature, pressure, and acoustic attenuation must be considered when calculating fluid velocity. The latter depends on the sound frequency and the properties of the specific fluid of interest. Experiments were assess undertaken to the performance of ultrasonic technology for liquid CO₂ measurements. The tests targeted CCS shipping and export pipeline conditions. Twenty static data points were collected at various fluid densities, see Fia. 3

Extended Abstract

The experiments were conducted at the laboratories of SINTEF in Trondheim, Norway. The unit was confined within a box with insulation and controlled heating. The enclosure was placed inside a temperature-controlled room, as illustrated in Fig. 4. The meter flowcell was filled with CO₂ (99.5%) purity). Measurements were acquired in decreasing order of density, starting at the lowest



Fig. 4 – Sketch of the experimental setup

temperature and moving towards higher temperatures and pressures. The data from the ultrasonic meter was acquired using PanaView®, the proprietary software with real-time flow data, historical tracking of diagnostics, and a full configuration audit trail.

3 Preliminary results and challenges

The attenuation of ultrasound signals through CO_2 , dominated by the fluid's molecular thermal relaxation properties [4], has previously been identified as a challenge for gaseous CO_2 service. Molecular thermal relaxation is less prominent for liquid than for gaseous CO_2 . The relaxation frequency is approximately proportional to density up to 900 kg·m⁻³ [5, 6]. The ultrasonic signals were strong

for most high-density points, enabling measurement through the medium. However, as the density of decreased, the liquid CO2 approaching that of gas, the signal degraded significantly (see Fig. 5). This signal degradation could be due to the proximity of the saturation liquid line. The effect of phase transitions during operations can be potentially overcome bv usina transducers of different frequencies depending on the fluid conditions.





Extended Abstract



measurements from EOS

The speed of sound measurements showed a positive bias compared to theoretical values from Wagner-Span EOS [7]. The measurement error increases beyond 4% at densities below 900 kg m⁻³ (see Fig. 6).

Two other challenges were identified apart from the bias in the speed of sound from theory. Firstly, higher acoustic impedance and better coupling were observed at higher densities, as indicated by the improved signal gain. Yet, compared to theory [6] [8], there is increased signal attenuation for any

given path length (see Fig. 7a). Secondly, the delta-time calculations, which under no-flow conditions should be very near to zero, present a more significant variance at lower densities (See Fig. 7b). The above further supports the hypothesis that possible changes in the fluid physical properties disrupt the ultrasonic signals' transmission causing signal degradation.



Fig. 7 – (a) Measurements gain and theoretical path attenuation (α*L_{path}) for all test points and transducer path T1 and (b) Maximum and minimum transit times across all transducer paths

Ensuring the quality of the processed signal is of paramount importance. Future experimental work should target conditions for CO_2 pipeline service for liquids at densities above 900 kg m⁻³ and close to saturated liquid conditions. The unique capabilities of ultrasonic flow meters (such as low-induced pressure drops and large flow capacities) make them valuable for use in the CCS chain. Hence, efforts are needed to overcome the technical challenges uncovered by this study. The value of such a study relies in a thorough analysis of the raw signals from which optimal processing of weaker acoustics can be realised.

4 NOTATION

The notation and symbols used in this paper are as follows:

Extended Abstract

- ∆t Transit time difference between up- and down-stream times
- t_{up} Through fluid transmission time in the upstream direction
- t_{dn} Through fluid transmission time in the downstream direction
- Path length Lpath between transducers Signal-to-noise ratio SNR T1-T4 Transducers chords 1 to 4 V Flow velocity Sound attenuation coefficient α Fluid density (kg m⁻³) ρ Transducer path angle θ

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